



Point on Wave Closing with Transformer - Basics

# SIPROTEC 5 Application

# Point on Wave Closing with Transformer - Basics

APN-071, Edition 1

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# 1 Point-on-Wave Closing with Transformer - Basics

#### 1.1 Introduction

On large transformers the in-rush current during energization is detrimental to the power system and the service life of the transformer. By timing the close command in each phase of the circuit breaker it is possible to minimize the in-rush current and the transient overvoltage.

The functionality used for this purpose in SIPROTEC 5 is the Point on Wave (PoW) switching.

Inrush current: reduced
 Voltage transients: reduced
 Maintenance intervals: increased

This application note will demonstrate the PoW function in SIPROTEC 5 devices, only the Close Command is considered in this application note in terms of the Point-on-Wave function.

### 1.2 Possible Device Types and Device Applications

The Point-on-Wave switching function can be applied in the following SIPROTEC 5 device types: 6MD86, 7SJ85, 7SA87, 7SD87, 7SL87, 7VK87, 7UT85, 7UT86, 7UT87, 6MU85, 7UM85.

3 different device applications are possible:

- Stand-alone point-on-wave (PoW) switching device, via the device type 6MD86
- Bay-control function and point-on-wave switching in one device, via the device type 6MD86
- Protection, bay-control function, and point-on-wave switching in one device, via the preceding listed devices

Additional function points must be considered for the Point-on-Wave Switching function. For each switching direction (closing or opening) one IO209 extension module with high-speed relays is required as well optionally a IO212 for fast measuring- transducer inputs. IO212 offers 8 fast measuring-transducer inputs, 3 of which are required for the reference contacts if applicable.

In case of non-Siemens circuit breakers, this function is carried out via the 52a auxiliary contact of the circuit breaker, which is connected to normal device binary inputs, for example, available in the 1/3 base module. No IO212 is required for this.

### 1.3 Timing

For the transformer closing, the PoW function has predefined timing. This timing is based on the flux that will be induced in the transformer core due to the closing of the pole (prospective flux) in relation to the flux that is already present prior to closing of the pole (remnant and/or dynamic flux). In this application remnant flux is not considered.

The timing of the 3 poles for closing with PoW can be checked in the settings (a modification is not required:

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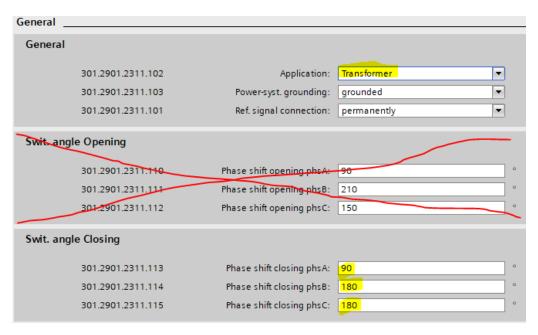


Figure 1: Timing of PoW closing - transformer

The switching angle at closing always refers to the reference voltage which is the Phase A voltage. The first phase will be A which closes at 90°; this is at the peak of the phase A voltage. The phase B and C follow with closing when the reference voltage is at 180° which is at the zero-crossing subsequent to 90°.

#### 1.4 Circuit Breaker

During closing the circuit breaker will go through the following stages (figure is copied from PoW manual description):

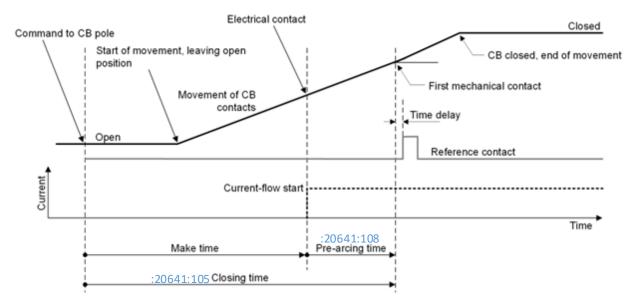


Figure 2: Timing of Circuit Breaker Closing

The PoW function must be set with the relevant circuit breaker data:

CB data			
301.2901.20641.105	CB closing time phsA:	8.2	ms
301.2901.20641.106	CB closing time phsB:	13.0	ms
301.2901.20641.107	CB closing time phsC:	13.4	ms
301.2901.20641.108	CB pre-arcing time phsA:	0.4	ms
301.2901.20641.109	CB pre-arcing time phsB:	0.1	ms
301.2901.20641.110	CB pre-arcing time phsC:	0.1	ms
301.2901.20641.115	CB correction time phsA:	2.00	ms
301.2901.20641.116	CB correction time phsB:	-2.00	ms
301.2901.20641.117	CB correction time phsC:	0.00	ms

Figure 3: Circuit Breaker settings

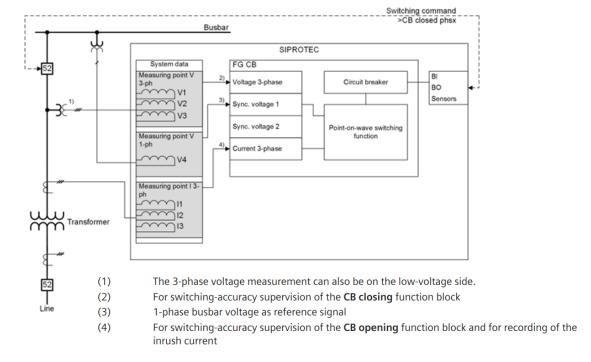
The above CB settings are for a CB model and are therefore not typical for real circuit breaker. The correction times set in the screenshot above adapt for deviation reference contact (auxiliary contact), i.e. the difference between the reference contact and the primary CB contact.

Parameter	Descripting	Setting	
_:105 CB closing time	Time between make of close contact in relay	Set this to the specified "tc" of the	
phs A	and first mechanical contact closing in CB	circuit breaker	
_:108 CB pre-arcing time	Time between first electrical contact in the CB	Set this to the specified pre-arc time	
phs A	and first mechanical contact closing in CB	of the circuit breaker.	
_:115 CB correction time	During commissioning small deviations from	Set to the deviation from the set	
phs A	the specified closing time may be determined	closing time as discovered during	
	and set here	commissioning	

The above table describes the CB timing settings for Phase A. The Phase B and C settings are set in the same manner.

#### 1.5 Connection

The transformer will be connected as follows:



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#### Figure 4: Transformer connection diagram

The phase selective close commands must be routed via high speed contacts (IO 209 Module). The bus voltage (Phase A) will be used as reference voltage: i.e. the voltage that controls the PoW closing commands.

Note that the busbar voltage, single phase connection must be assigned to Vsync 1 of the circuit breaker:

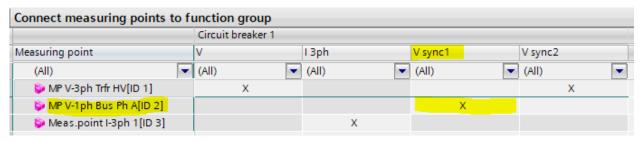


Figure 5: Assignment of Measuring points

The following settings allow the configuration of supervision boundaries for the reference voltage:

Supervision			
301.2901.2311.130	Frequency lower limit:	49.00	Hz
301.2901.2311.131	Frequency upper limit:	51.00	Hz
301.2901.2311.132	Min. reference voltage:	15.000	V
301.2901.2311.133	ΔT zero crossing min.:	9.0	ms
301.2901.2311.134	ΔT zero crossing max.:	11.0	ms
301.2901.2311.135	Zero-crossing sup. T-hold:	0.10	s
301.2901.2311.136	CB interm.pos. max. time:	5.00	s

Figure 6: Setting of supervision boundaries

For this application at 50 Hz, the default settings are applied. The  $\Delta T$  of the zero crossings checks the interval between successive zero crossings. Expected is 10 ms at 50 Hz. The holding time delays the drop out once a  $\Delta T$  outside the set boundaries has been detected. Refer to the manual for more details.

#### Must the close command be processed when PoW closing is not possible?

When the reference voltage is not present or disturbed a controlled PoW closing is not possible. From an operational point of view, it may however be desirable to still process the close commend (3 pole). This can be set with the following parameter:

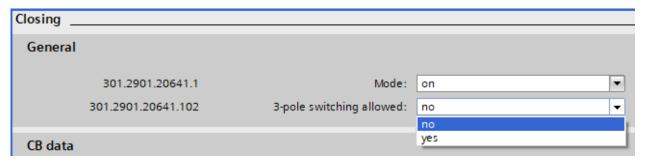


Figure 7: Closing 3-pol when PoW is not possible

Set :102 3-pole switching allowed = yes to allow 3 pole closing when PoW is not possible.

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During the PoW closing relevant information should be routed to the operational log. It may be advisable to trigger a fault record in order to check the operation. If a fault record is triggered the PoW signals can be routed to the "Fault Log" which will be opened together with the fault record. In this manner the data can be processed more easily. The following CFC block can be used to trigger the fault record:

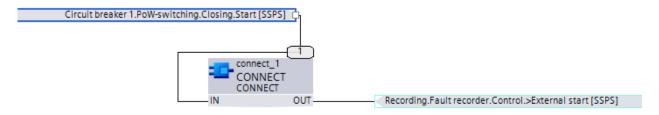


Figure 8: CFC logic for triggering Fault Record with PoW closing

The following settings allow the configuration of the boundaries of the PoW closing. When exceeded a corresponding indication is provided (checks correct response of Circuit Breaker).

Swit.accuracy sup.			
301.2901.20641.114	Maximum allowed time:	0.30	s
301.2901.20641.129	Clos. time: allowed diff. :	3.0	ms
301.2901.20641.130	Make time: allowed diff.:	3.0	ms
301.2901.20641.144	Make-time detection via:	voltage ▼	
301.2901.20641.135	Make-time detec. V> phsA:	40.000	V
301.2901.20641.136	Make-time detec. V> phsB:	40.000	V
301.2901.20641.137	Make-time detec. V> phsC:	40.000	V
301.2901.20641.138	Threshold: V too high:	120.000	V
301.2901.20641.139	Threshold: I too high:	2.000	Α

Figure 9: Settings of switching accuracy supervision

For more details on the above settings refer to the manual. In this application with closing of a transformer the "Make-time detection" is fixed via "voltage". When the 1st pole closes there will be induced voltage in the other 2 phases; this is not used for closing detection. When these poles close there will be a significant jump. (refer to Figure 14 Fault Record) For a rated secondary Ph-Ph voltage of 100 V the setting of 40 V is approximately 50% of the peak instantaneous voltage – this is OK, in some cases an increase may be advisable.

If the PoW closing works correctly there will be very little transient overvoltage. The threshold "V too high" sets the boundary. If a Voltage exceeds this threshold (instantaneous) a corresponding alarm is initiated. The current threshold is not relevant here as the voltage is used for the PoW closing of transformers.

### 1.6 Routing Matrix

Apart from the standard signal routing (CB auxiliary contacts, tripping etc.) the PoW closing requires the routing of the high-speed contacts of the IO 209 Module:

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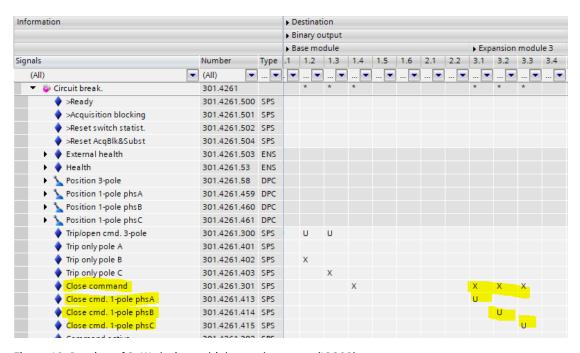


Figure 10: Routing of PoW closing to high speed contacts (IO209)

As the closing triggers a fault record via CFC in this application, the PoW signals should be routed to the Fault Log and Recorder:

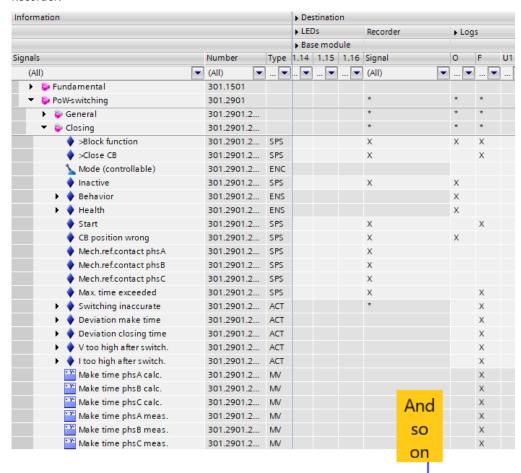


Figure 11: Routing of PoW signals to Fault Log and Recorder

#### 1.7 Commissioning

Once the settings are applied, the 1st closing operation must be recorded and evaluated. In the log below the relevant time values for analysis are provided. These can be used to check the correct close timing of the circuit breaker (Figure 2 above).

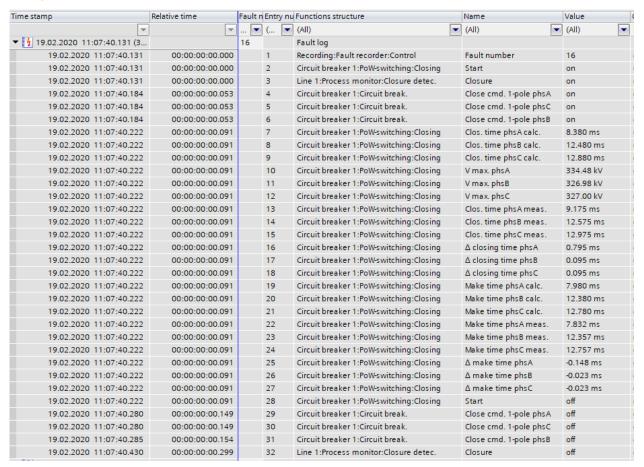


Figure 12: Fault Log of PoW close sequence

The information from this 1st closing operation are entered in Excel:

Pole	Set Clos.	Set Pre arc	Calc. Make	Meas. Clos.	Meas. Make
	Time	Time	Time	Time	Time
Α	8,380	0,400	7,980	9,175	7,832
В	12,480	0,100	12,380	12,575	12,357
С	12,880	0,100	12,780	12,975	12,757

The calculated make time is the set closing time – set Pre-arc time.

The measured make time is obtained by monitoring the measured voltage.

The measured closing time is obtained by monitoring the auxiliary contact.

A comparison of the set and measured values allows checking that the application is working as expected.

The above results are shown in the following graph for easy comparison:

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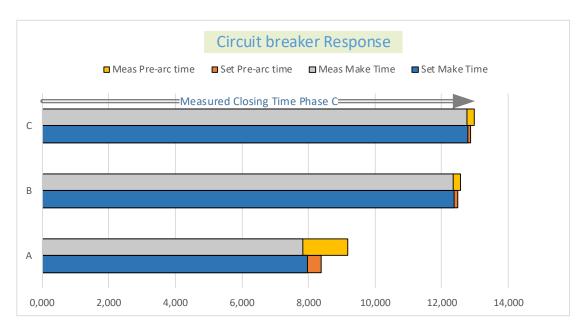


Figure 13: Set and measured CB operating times

The set and measured values have a good correlation so that the application can be considered as working as correctly.

A further method of checking the PoW closing is by analyzing the fault record:

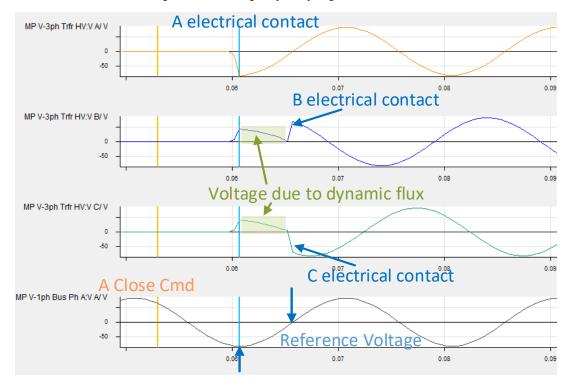


Figure 14: Fault record of CB closing sequence

The record confirms the correct initial electrical contact in phase A at the negative voltage peak of the reference voltage. Subsequently the phases B and C measure a voltage opposite to phase A and with half the magnitude; this is due to the dynamic flux. At the zero crossing of the reference voltage the phases B and C have initial electrical contact.

Based on the results from the fault log and the record, the correct operation of the PoW closing can be confirmed. If there is a significant deviation, the CB must be checked, and the settings adjusted accordingly.

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#### 1.8 Conclusion

The Point-on-wave switching function in SIPROTEC 5 is used to reduce increased electrodynamic and dielectric loads which are caused by non-optimal switching of circuit breakers in the network. In extreme cases, these loads reduce the reliability and life of the equipment installed in the network or lead to unnecessary opening operations by the protection device. To avoid effects such as over-voltages and inrush currents, this function can control the closing and opening instants of circuit breakers.

This basic example demonstrated how PoW closing on a transformer can be applied and checked. It shows all the key steps required in the implementation. Additional features such as adapting the timing to environmental conditions or the consideration remnant flux are not covered. Further information covering these aspects is planned.

Published by Siemens AG

Smart Infrastructure Digital Grid Humboldtstrasse 59 90459 Nuremberg, Germany

20 122 11a.c....2019, 20111a...

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For the U.S. published by Siemens Industry Inc.

100 Technology Drive Alpharetta, GA 30005 United States

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